Logix5000 Controllers Messages

Important user information

Read this document and the documents listed in the additional resources section about installation, configuration, and operation of this equipment before you install, configure, operate, or maintain this product. Users are required to familiarize themselves with installation and wiring instructions in addition to requirements of all applicable codes, laws, and standards.

Activities including installation, adjustments, putting into service, use, assembly, disassembly, and maintenance are required to be carried out by suitably trained personnel in accordance with applicable code of practice. If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

No patent liability is assumed by Rockwell Automation, Inc. with respect to use of information, circuits, equipment, or software described in this manual.

Reproduction of the contents of this manual, in whole or in part, without written permission of Rockwell Automation, Inc., is prohibited.

Throughout this manual, when necessary, we use notes to make you aware of safety considerations.

---

**WARNING:** Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

---

**ATTENTION:** Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you identify a hazard, avoid a hazard, and recognize the consequence.

---

**Important:** Identifies information that is critical for successful application and understanding of the product.

---

Labels may also be on or inside the equipment to provide specific precautions.

---

**SHOCK HAZARD:** Labels may be on or inside the equipment, for example, a drive or motor, to alert people that dangerous voltage may be present.

---

**BURN HAZARD:** Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.

---

**ARC FLASH HAZARD:** Labels may be on or inside the equipment, for example, a motor control center, to alert people to potential Arc Flash. Arc Flash will cause severe injury or death. Wear proper Personal Protective Equipment (PPE). Follow ALL Regulatory requirements for safe work practices and for Personal Protective Equipment (PPE).
The following table contains the changes made to this revision.

<table>
<thead>
<tr>
<th>Change</th>
<th>Topic</th>
</tr>
</thead>
<tbody>
<tr>
<td>Updated sample project folder location.</td>
<td>&quot;Introduction (on page 23)&quot;</td>
</tr>
</tbody>
</table>
## Table of contents

### Preface
- Studio 5000 environment ................................................................. 7
- Additional resources ................................................................. 8

### Controller messages
- Introduction ........................................................................... 9
- Supported data types ........................................................... 9
- Message queue .................................................................. 10
- Cache list ............................................................................. 11
- Unconnected buffers .......................................................... 12
- Guidelines .......................................................................... 13
- Get or set the number of unconnected buffers ..................... 14
  - Get the number of unconnected buffers .......................... 14
  - Set the number of unconnected buffers ......................... 15
- Convert between INTs and DINTs ......................................... 16

### Manage multiple messages
- Introduction ........................................................................ 19
- Message manager logic ....................................................... 19

### Chapter 2
- Message manager logic ....................................................... 19

### Chapter 3
- Send a message to multiple controllers
  - Introduction ..................................................................... 23
  - Configure the I/O configuration ........................................ 24
  - Define your source and destination elements .................... 24
  - Create the MESSAGE CONFIGURATION data type ............ 25
  - Create the configuration array ........................................ 26
  - Get the size of the local array ........................................... 28
  - Load the message properties for a controller .................... 28
  - Configure the message .................................................... 29
  - Step to the next controller ............................................. 29
  - Restart the sequence ...................................................... 30

### Index
This manual shows how to program message (MSG) instructions to and from Logix5000™ controllers. This manual is one of a set of related manuals that show common procedures for programming and operating Logix5000 controllers.

For a complete list of common procedures manuals, refer to the Logix5000 Controllers Common Procedures Programming Manual, publication 1756-PM001.

The term Logix5000 controller refers to any controller that is based on the Logix5000 operating system.

The Studio 5000 Automation Engineering & Design Environment™ combines engineering and design elements into a common environment. The first element is the Studio 5000 Logix Designer™ application. The Logix Designer application is the rebranding of RSLogix™ 5000 software and will continue to be the product to program Logix5000™ controllers for discrete, process, batch, motion, safety, and drive-based solutions.

The Studio 5000 environment is the foundation for the future of Rockwell Automation® engineering design tools and capabilities. The Studio 5000 environment is the one place for design engineers to develop all elements of their control system.
Additional resources

These documents contain additional information concerning related Rockwell Automation products.

<table>
<thead>
<tr>
<th>Resource</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Industrial Automation Wiring and Grounding Guidelines, publication 1770-4.1</td>
<td>Provides general guidelines for installing a Rockwell Automation industrial system.</td>
</tr>
</tbody>
</table>

You can view or download publications at [http://www.rockwellautomation.com/literature](http://www.rockwellautomation.com/literature). To order paper copies of technical documentation, contact your local Rockwell Automation distributor or sales representative.
Chapter 1

Controller messages

Introduction

This section describes how to transfer (send or receive) data between controllers by executing a message (MSG) instruction. It explains cache connections and buffers so you can correctly program the controller.

Supported data types

The following data types are supported when sending CIP messages.

- SINT
- INT
- DINT
- LINT
- REAL

In addition, you can send a message with any structure type that is predefined, module-defined, or user-defined.

See “Convert between INTs and DINTs (on page 16)” for more information on INTs and DINTs.

For complete details on programming a message instruction, see the Logix5000 Controllers General Instruction Reference Manual, publication 1756-RM003.

Example: Execute a Message (MSG) Instruction

If count_send = 1
and count_msg.EN = 0 (MSG instruction is not enabled)
then execute a MSG instruction that sends data to another controller.
This diagram shows how the controller processes MSG instructions.

1. The controller scans the MSG instruction and its rung-condition-in goes true. The message passes to a throttle that has 16 positions. If the throttle is full, the message remains enabled but is held until another controller scan.

2. The System-overhead time slice executes and the message is pulled from the throttle to the message queue.

3. **If the MSG instruction**
   - **Then the MSG instruction**
     - Does not use a connection or the connection was not previously cached
       - Uses an unconnected buffer to establish communication with the destination device.
     - Uses a connection and the connection is cached
       - Does not use an unconnected buffer.

4. Communication occurs with the destination device.

**Message queue**

The message queue holds up to 48 MSG instructions, including those that you configure as a block-transfer read or block-transfer write. When the queue is full, an instruction tries to enter the queue on each subsequent scan of the instruction, as shown in the following illustration.
Description

1. The controller scans the MSG instruction.
   The rung-condition-in for the MSG instruction is true.
   The EN bit is set.
   The MSG instruction attempts to enter the queue but 16 throttle positions exist. If all 16 are filled and a
   17th message is executed, the message is enabled.
   The EW bit remains cleared.

2 & 3. The controller scans the MSG instruction.
   The rung-condition-in for the MSG instruction is false.
   The EN bit remains set.
   The MSG instruction attempts to pass through the throttle, but no open positions exist yet.
   The EW bit remains cleared.

4. The controller scans the MSG instruction.
   The MSG instruction attempts to enter the queue. This time the throttle position is open and the message
   can pass to the message queue.
   The EW bit is set.

Cache list

Depending on how you configure a MSG instruction, it may use a connection to send or receive data.

<table>
<thead>
<tr>
<th>This type of message</th>
<th>And this communication method</th>
<th>Uses a connection</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIP data table read or write</td>
<td>—</td>
<td>Your option(^{(1)})</td>
</tr>
<tr>
<td>PLC-2, PLC-3, PLC-5, or SLC (all types)</td>
<td>CIP</td>
<td>No</td>
</tr>
<tr>
<td></td>
<td>CIP with Source ID</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DH+</td>
<td>Yes</td>
</tr>
<tr>
<td>CIP generic</td>
<td>—</td>
<td>Your option(^{(2)})</td>
</tr>
<tr>
<td>Block-transfer read or write</td>
<td>—</td>
<td>Yes</td>
</tr>
</tbody>
</table>

\(^{(1)}\) CIP data table read or write messages can be connected or unconnected. However for most applications, it is recommended you leave CIP data table read or write messages connected.

\(^{(2)}\) CIP generic messages can be connected or unconnected. However for most applications, it is recommended you leave CIP generic messages unconnected, unless you want to use the Large Connection option.

If a MSG instruction uses a connection, you have the option to leave the connection open (cache) or close the connection when the message is done transmitting.

<table>
<thead>
<tr>
<th>If you</th>
<th>Then</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cache the connection</td>
<td>The connection stays open after the MSG instruction is done. This optimizes execution time. Opening a connection each time the message executes increases execution time.</td>
</tr>
<tr>
<td>Do not cache the connection</td>
<td>The connection closes after the MSG instruction is done. This frees up that connection for other uses.</td>
</tr>
</tbody>
</table>
The controller has the following limits on the number of connections that you can cache.

<table>
<thead>
<tr>
<th>If you have this software version and firmware revision</th>
<th>Then you can cache</th>
</tr>
</thead>
<tbody>
<tr>
<td>11.x or earlier</td>
<td>• Block transfer messages for up to 16 connections.</td>
</tr>
<tr>
<td></td>
<td>• Other types of messages for up to 16 connections.</td>
</tr>
<tr>
<td>12.x or later</td>
<td>Up to 32 connections.</td>
</tr>
</tbody>
</table>

If several messages go to the same device, the messages may be able to share a connection.

<table>
<thead>
<tr>
<th>If the MSG instructions are to and they are</th>
<th>Then</th>
</tr>
</thead>
<tbody>
<tr>
<td>Different devices</td>
<td>Each MSG instruction uses 1 connection.</td>
</tr>
<tr>
<td>The same device, cached, and not a large connection</td>
<td>Each MSG instruction uses 1 connection and 1 cached buffer.</td>
</tr>
<tr>
<td></td>
<td>Not enabled simultaneously All MSG instructions use 1 connection and 1 cached buffer. They share the connection and the buffer.</td>
</tr>
<tr>
<td>The same device, cached, and a large connection</td>
<td>Each MSG instruction uses 1 connection and 1 cached buffer.</td>
</tr>
<tr>
<td></td>
<td>Not enabled simultaneously All MSG instructions use 1 connection and 1 cached buffer. They share the connection and the buffer.</td>
</tr>
</tbody>
</table>

Example: Share a connection
- If the controller alternates between sending a block-transfer read message and a block-transfer write message to the same module, then together the messages count as one connection. Caching both messages counts as one on the cached buffer.
- If the controller sends 10 cached connected messages to the same bridge module (for example, 1756-EN2T) where 7 utilize a standard connection (large connection unchecked) and 3 utilize a large connection, then the 7 standard connection messages all utilize one cached connection. The 3 large connection messages all utilize another cached connection. In total, the 10 messages use 2 cached connections.

Unconnected buffers

To establish a connection or process unconnected messages, the controller uses an unconnected buffer.

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unconnected buffer</td>
<td>An allocation of memory that the controller uses to process unconnected communication. The controller performs unconnected communication when it:</td>
</tr>
<tr>
<td></td>
<td>• Establishes a connection with a device, including an I/O module.</td>
</tr>
<tr>
<td></td>
<td>• Executes a MSG instruction that does not use a connection.</td>
</tr>
</tbody>
</table>
The controller can have 10 to 40 unconnected buffers.
- The default number is 10.
- To increase the number of unconnected buffers, execute a MSG instruction that reconfigures the number of unconnected buffers.
- Each unconnected buffer uses 1.2 KB of memory.
- If all unconnected buffers are in use when an instruction leaves the message queue, an error occurs and data does not transfer.

If a MSG instruction uses a connection, the instruction uses an unconnected buffer when it first executes to establish a connection. If you configure the instruction to cache the connection, it no longer requires an unconnected buffer once the connection is established.

As you plan and program your MSG instructions, follow these guidelines.

<table>
<thead>
<tr>
<th>Guideline</th>
<th>Details</th>
</tr>
</thead>
</table>
| For each MSG instruction, create a control tag. | • Data type = MESSAGE  
• Scope = controller  
• The tag cannot be part of an array or a user-defined data type. |
| Keep the source and destination data at the controller scope. | A MSG instruction can access only tags that are in the Controller Tags folder (controller scope). |
| If your message is to a device that uses 16-bit integers, such as a PLC-5 or SLC 500 controller, and it transfers integers (not REALs), use a buffer of INTs in the message and DINTs throughout the project. | Logix5000 controllers execute more efficiently and use less memory when working with 32-bit integers (DINTs). See "Convert between INTs and DINTs (on page 16)". |
| Cache the connection for those MSG instructions that execute most frequently, up to the maximum number permissible for your controller revision. | Execution time is optimized when the controller does not open a connection each time the message executes. |
| If you want to enable more than 16 MSGs at one time, use a management strategy to ensure some MSG instructions are not delayed entering the queue. | To guarantee the execution of each message, use one of these options:  
• Enable each message in sequence.  
• Enable the messages in groups.  
• Program a message to communicate with multiple devices.  
• Program logic to coordinate the execution of messages. |
| Keep the number of unconnected and uncached MSGs less than the number of unconnected buffers. | The controller can have 10 to 40 unconnected buffers. The default number is 10.  
• If all unconnected buffers are in use when an instruction leaves the message queue, an error occurs, the data is not transferred.  
• You can increase the number of unconnected buffers (up to 40), provided you continue to adhere to the previous guideline.  
• To increase the number of unconnected buffers, see “Get or set the number of unconnected buffers (on page 14)”.

Guidelines

Rockwell Automation Publication 1756-PM012F-EN-P - October 2014
Get or set the number of unconnected buffers

To determine or change the number of unconnected buffers, use a MSG instruction.

- The range is 10 to 40 unconnected buffers.
- The default number is 10.
- Each unconnected buffers uses 1.1 KB of memory.

Get the number of unconnected buffers

To determine the number of unconnected buffers that are currently available, configure a Message (MSG) instruction as follows.

<table>
<thead>
<tr>
<th>On this tab</th>
<th>For this item</th>
<th>Type or choose</th>
</tr>
</thead>
<tbody>
<tr>
<td>Configuration</td>
<td>Message Type</td>
<td>CIP Generic</td>
</tr>
<tr>
<td></td>
<td>Service Type</td>
<td>Custom</td>
</tr>
<tr>
<td></td>
<td>Service Code</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td>Class</td>
<td>304</td>
</tr>
<tr>
<td></td>
<td>Instance</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>Attribute</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>Source Element</td>
<td>source_array where data type = SINT(4)</td>
</tr>
<tr>
<td></td>
<td>In this element</td>
<td>Enter</td>
</tr>
<tr>
<td></td>
<td>source_array(0)</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>source_array(1)</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>source_array(2)</td>
<td>17</td>
</tr>
<tr>
<td></td>
<td>source_array(3)</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>Source Length (bytes)</td>
<td>4 (Write 4 SINTs.)</td>
</tr>
<tr>
<td></td>
<td>Destination Element</td>
<td>destination_array where data type = SINT(10) (Leave all values = 0.)</td>
</tr>
<tr>
<td></td>
<td>destination_array(6) = current number of unconnected buffers</td>
<td></td>
</tr>
<tr>
<td>Communication</td>
<td>Path</td>
<td>1, slot_number_of_controller</td>
</tr>
</tbody>
</table>
Set the number of unconnected buffers

As a starting value, set the number of unconnected buffers equal to the number of unconnected and uncached messages enabled at one time plus 5. The additional 5 buffers provide a cushion in case you underestimate the number of messages that are enabled at once.

To change the number of unconnected buffers of the controller, configure a Message (MSG) instruction as follows.

<table>
<thead>
<tr>
<th>On this tab</th>
<th>For this item</th>
<th>Type or select</th>
</tr>
</thead>
<tbody>
<tr>
<td>Configuration</td>
<td>Message Type</td>
<td>CIP Generic</td>
</tr>
<tr>
<td></td>
<td>Service Type</td>
<td>Custom</td>
</tr>
<tr>
<td></td>
<td>Service Code</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td>Class</td>
<td>304</td>
</tr>
<tr>
<td></td>
<td>Instance</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>Attribute</td>
<td>0</td>
</tr>
<tr>
<td>Source Element</td>
<td>source_array where data type = SINT[8]</td>
<td></td>
</tr>
<tr>
<td>In this element</td>
<td>Enter</td>
<td></td>
</tr>
<tr>
<td></td>
<td>source_array[0]</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>source_array[1]</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>source_array[2]</td>
<td>17</td>
</tr>
<tr>
<td></td>
<td>source_array[3]</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>source_array[4]</td>
<td>Number of unconnected buffers that you want.</td>
</tr>
<tr>
<td></td>
<td>source_array[5]</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>source_array[6]</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>source_array[7]</td>
<td>0</td>
</tr>
<tr>
<td>Source Length (bytes)</td>
<td>8 (Write 8 SINTs.)</td>
<td></td>
</tr>
<tr>
<td>Destination Element</td>
<td>destination_array where data type = SINT[6] (Leave all the values = 0.)</td>
<td></td>
</tr>
<tr>
<td>Communication</td>
<td>Path</td>
<td>1, slot_number_of_controller</td>
</tr>
</tbody>
</table>

Example: Set the number of unconnected buffers

If S:FS = 1 (first scan)
then set the number of unconnected buffers for the controller.

Source_Array[0] = 1
Source_Array[0] = 1
Source_Array[1] = 0
Source_Array[2] = 17
Source_Array[3] = 0
Source_Array[4] = Number of unconnected buffers that you want.
Source_Array[5] = 0
Source_Array[6] = 0
Source_Array[7] = 0

If UCB_Set.EN = 0 (MSG instruction is not already enabled)
then MSG instruction sets the number of unconnected buffers = Source_Array[4].
Tag Name | Type  | Description
----------|-------|-------------
UCB_Set   | MESSAGE | Control tag for the MSG instruction.
Source_Array | SINT[8] | Source values for the MSG instruction, including the number of unconnected buffers that you want.

### Convert between INTs and DINTs

In the Logix5000 controller, use the DINT data type for integers whenever possible. Logix5000 controllers execute more efficiently and use less memory when working with 32-bit integers (DINTs).

If your message is to a device that uses 16-bit integers, such as a PLC-5 or SLC 500 controller, and it transfers integers (not REALs), use a buffer of INTs in the message and DINTs throughout the project. This increases the efficiency of your project.

#### Read 16-bit integers

<table>
<thead>
<tr>
<th>Data from the device</th>
<th>Buffer of INTs</th>
<th>DINTs for use in the project</th>
</tr>
</thead>
<tbody>
<tr>
<td>Word 1</td>
<td>INT_Buffer[0]</td>
<td>DINT_Array[0]</td>
</tr>
<tr>
<td>Word 2</td>
<td>INT_Buffer[1]</td>
<td>DINT_Array[1]</td>
</tr>
</tbody>
</table>

**Description**

1. The Message (MSG) instruction reads 16-bit integers (INTs) from the device and stores them in a temporary array of INTs.
2. A File Arith/Logical (FAL) instruction converts the INTs to DINTs for use by other instructions in your project.
Write 16-bit integers

<table>
<thead>
<tr>
<th>DINTs from the project</th>
<th>Buffer of INTs</th>
<th>Data for the device</th>
</tr>
</thead>
<tbody>
<tr>
<td>DINT_Array[0]</td>
<td>INT_Buffer[0]</td>
<td>Word 1</td>
</tr>
</tbody>
</table>

Description
1. An FAL instruction converts the DINTs from the Logix5000 controller to INTs.
2. The MSG instruction writes the INTs from the temporary array to the device.

Example: Read integer values from a PLC-5 controller
If Condition_1 = 1
and Msg_1.EN = 0 (MSG instruction is not enabled)
then read 3 integers from the PLC-5 controller and store them in INT_Buffer (3 INTs).

If Msg_1.DN = 1 (MSG instruction has read the data)
then reset the FAL instruction.
The FAL instruction sets DINT_Array = INT_Buffer. This converts the values to 32-bit integers (DINTs).
Example: Write integer values to a PLC-5 controller

If Condition_2 = 1
then reset the FAL instruction.

The FAL instruction sets INT_Buffer = DINT_Array. This converts the values to 16-bit integers (INTs).

If Control_2.DN = 1 (FAL instruction has converted the DINTs to INTs)
and Msg_2.EN = 0 (MSG instruction is not enabled)
then write the integers in INT_Buffer (3 INTs) to the PLC-5 controller.
Manage multiple messages

Introduction

You can use ladder logic to send groups of message (MSG) instructions in sequence.

- To be processed, each MSG instruction must enter the message queue.
- The queue holds 48 MSGs.
- If more than 16 MSGs are enabled at one time, the message throttle prevents some of the messages from entering the message queue. If this occurs, the MSG is held until room exists on the queue for the controller to process the MSG. On each subsequent scan of the MSG, it checks the queue to see if room exists.

The message manager logic lets you control the number of MSGs that are enabled at one time and enable subsequent MSGs in sequence. In this way, MSGs enter and exit the queue in order and do not need to wait for room on the queue to become available.

Message manager logic

The message manager logic sends three groups of MSGs. Use as many groups as needed to include all your MSGs.

The Msg_Group tag controls the enabling of each MSG.

- The tag uses the DINT data type.
- Each bit of the tag corresponds to a group of MSGs. For example, Msg_Group.0 enables and disables the first group of MSGs (group 0).

Example: Message manager logic

To make the example easier to follow, each group contains only two MSGs. In your project, use more MSGs in each group, such as five.

Initialize the logic

If S:FS = 1 (first scan)
then initialize the MSGs:

- Msg_Group = 0, which disables all MSGs.
- Msg_Group.0 = 1, which enables the first group of MSGs.
**Restart the sequence**

If the MSGs in group 2 (last group) are currently enabled (Msg_Group.2 = 1)
and Msg_4 is in the state of done or error
and Msg_5 is in the state of done or error
then restart the sequence of MSGs with the first group:
Msg_Group.2 = 0. This disables the last group of MSGs.
Msg_Group.0 = 1. This enables the first group of MSGs.

**Send the first group of MSGs**

If Msg_Group.0 changes from 0 -> 1 then
send Msg_0.
send Msg_1.

Because a MSG instruction is a transitional instruction, it executes only when its rung-condition-in changes from false to true.

**Enable the second group of MSGs**

If the MSGs in group 0 are currently enabled (Msg_Group.0 = 1)
and Msg_0 is in the state of done or error
and Msg_1 is in the state of done or error
then:
Msg_Group.0 = 0. This disables the current group of MSGs.
Msg_Group.1 = 1. This enables the next group of MSGs.
Send the second group of MSGs
If Msg_Group.1 changes from 0 \rightarrow 1 then
  send Msg_2.
  send Msg_3.

Enable the next group of MSGs
If the MSGs in group 1 are currently enabled (Msg_Group.1 = 1)
and Msg_2 is in the state of done or error
and Msg_3 is in the state of done or error
then:
  Msg_Group.1 = 0. This disables the current group of MSGs.
  Msg_Group.2 = 1. This enables the next group of MSGs.

Send the next group of MSGs
If Msg_Group.1 changes from 0 \rightarrow 1 then
  send Msg_2.
  send Msg_3.
Send a message to multiple controllers

Introduction

You can program one message instruction to communicate with multiple controllers. To reconfigure a MSG instruction during runtime, write new values to the members of the MESSAGE data type.

Important: In the MESSAGE data type, the RemoteElement member stores the tag name or address of the data in the controller that receives the message.

<table>
<thead>
<tr>
<th>If the message</th>
<th>Then the RemoteElement is the</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reads data</td>
<td>Source element</td>
</tr>
<tr>
<td>Writes data</td>
<td>Destination element</td>
</tr>
</tbody>
</table>

![Diagram showing Message Configuration - message](image)

**A** If you use an asterisk [*] to designate the element number of the array, the value in **B** provides the element number.

**B** The Index box is available only when you use an asterisk [*] in the Source Element or Destination Element. The instruction substitutes the value of Index for the asterisk [*].

Tip: To copy the previous components from a sample project, take these steps.

A. On the Help menu, click Quick Start.

B. On the Quick Start window, in the left navigation pane, expand Controller Projects, and then click Open Sample Project.

C. In the Open Project dialog box, click MSG_To_multiple.Controllers.acd, and click Open.
Configure the I/O configuration

Although not required, it is recommended that you add the communication modules and remote controllers to the I/O configuration of the controller. This makes it easier to define the path to each remote controller.

For example, once you add the local communication module, the remote communication module, and the destination controller, clicking Browse lets you select the destination.

Define your source and destination elements

An array stores the data that is read from or written to each remote controller. Each element in the array corresponds to another remote controller.

1. Use the following worksheet to organize the tag names in the local and remote controllers.

<table>
<thead>
<tr>
<th>Name of Remote Controller</th>
<th>Tag or Address of Data in Remote Controller</th>
<th>Tag in This Controller</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>local_array[0]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>local_array[1]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>local_array[2]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>local_array[3]</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
2. Create the local_array tag, which stores the data in this controller.

<table>
<thead>
<tr>
<th>Tag Name</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>local_array</td>
<td>data_type [length]</td>
</tr>
<tr>
<td></td>
<td>where:</td>
</tr>
<tr>
<td></td>
<td>data_type is the data type of the data</td>
</tr>
<tr>
<td></td>
<td>that the message sends or receives, such</td>
</tr>
<tr>
<td></td>
<td>as DINT, REAL, or STRING.</td>
</tr>
<tr>
<td></td>
<td>length is the number of elements in the</td>
</tr>
<tr>
<td></td>
<td>local array.</td>
</tr>
</tbody>
</table>

Create the MESSAGE_CONFIGURATION data type

Create a user-defined data type to store the configuration variables for the message to each controller.

- Some of the required members of the data type use a string data type.
- The default STRING data type stores 82 characters.
- If your paths or remote tag names or addresses use less than 82 characters, you have the option of creating a new string type that stores fewer characters. This lets you conserve memory.
- To create a string type, click File > New Component > String Type.
- If you create a string type, use it in place of the STRING data type.

To store the configuration variables for the message to each controller, create the following user-defined data type.

**Data Type: MESSAGE_CONFIGURATION**

<table>
<thead>
<tr>
<th>Name</th>
<th>Data Type</th>
<th>Style</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Path</td>
<td>STRING</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RemoteElement</td>
<td>STRING</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Create the configuration array

Store the configuration properties for each controller in an array. Before each execution of the MSG instruction, your logic loads new properties into the instruction. This sends the message to another controller.

1. To store the configuration properties for the message, create the following array.

<table>
<thead>
<tr>
<th>Tag Name</th>
<th>Type</th>
<th>Scope</th>
</tr>
</thead>
<tbody>
<tr>
<td>message_config</td>
<td>MESSAGE_CONFIGURATION<a href="1">number</a></td>
<td>Any</td>
</tr>
</tbody>
</table>

(1) Number indicates the number of controllers to send the message

2. In the message_config array, enter the path to the first controller that receives the message.
Example:

<table>
<thead>
<tr>
<th>Type the path to the remote controller.</th>
<th>Message Path Browser</th>
</tr>
</thead>
<tbody>
<tr>
<td>or</td>
<td>peer_controller</td>
</tr>
<tr>
<td>Browse to the remote controller.</td>
<td>I/O Configuration</td>
</tr>
</tbody>
</table>

3. In the message_config array, enter the tag name or address of the data in the first controller to receive the message. Enter the path and remote element for each additional controller.

4. Enter the path and remote element for each additional controller.
Get the size of the local array

The SIZE instruction:

- Counts the number of elements in local_array.
- Counts the number of elements in Dimension 0 of the array. In this case, that is the only dimension.

Local_array_length (DINT) stores the size (number of elements) of local_array. This value tells a subsequent rung when the message is sent to all controllers and to start with the first controller again.

Load the message properties for a controller

1. The XIO instruction conditions the rung to continuously send the message.

2. The first COP instruction loads the path for the message. The value of index determines which element the instruction loads from message_config. The instruction loads one element from message_config.

3. The second COP instruction loads the tag name or address of the data in the controller that receives the message. The value of index determines which element the instruction loads from message_config. The instruction loads one element from message_config.
Configure the message

The following table explains how to configure the message.

<table>
<thead>
<tr>
<th>On this tab</th>
<th>If you want to</th>
<th>For this item</th>
<th>Type or select</th>
</tr>
</thead>
<tbody>
<tr>
<td>Configuration</td>
<td>Read (receive) data from the other controllers</td>
<td>Message Type</td>
<td>The read-type that corresponds to the other controllers</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Source Element</td>
<td>Tag or address that contains the data in the first controller</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Number Of Elements</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Destination Element</td>
<td>local_array[*]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Index</td>
<td>0</td>
</tr>
<tr>
<td>Write (send) data to the other controllers</td>
<td>Message Type</td>
<td>The write-type that corresponds to other controllers</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Source Element</td>
<td>local_array[*]</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Index</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Number Of Elements</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Destination Element</td>
<td>Tag or address that contains the data in the first controller</td>
<td></td>
</tr>
<tr>
<td>Communication</td>
<td>—</td>
<td>Path</td>
<td>Path to the first controller</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Cache Connections</td>
<td>Clear the Cache Connections check box (more efficient since this procedure continuously changes the path of the message)</td>
</tr>
</tbody>
</table>

Step to the next controller

After the MSG instruction sends the message, the following actions occur.

1. The first ADD instruction increments the index. This lets the logic load the configuration properties for the next controller into the MSG instruction.

2. The second ADD instruction increments the LocalIndex member of the MSG instruction. This lets the logic load the value from the next controller into the next element of local_array.
Restart the sequence

When the index equals the local_array_length, the controller sends the message to all other controllers.

1. The first CLR instruction sets the index equal to 0. This lets the logic load the configuration properties for the first controller into the MSG instruction and start the sequence of messages again.

2. The second CLR instruction sets the LocalIndex member of the MSG instruction equal to 0. This lets the logic load the value from the first controller into the first element of local_array.
Index

A
array
   controller configuration  26

B
block transfer
   guidelines  13
buffer
   for unconnected messages  12, 14

C
cache
   connection  11
communicate
   message instruction  9
   other controllers  9
connection
   cache  11
controller
   message properties  28
   messages  9

D
data type
   convert data  16
   message configuration  25

G
guidelines
   messages  13

L
ladder logic
   manage messages  19

M
message
   cache connection  11
   controller  9
   convert between 16 and 32-bit data  16
   example illustration  9
   limits  10
   manage multiple messages  19
   processing  9
   queue  10
   to a single controller  9
   to multiple controllers  23
   unconnected buffer  12, 14

P
processing
   message  9

Q
queue
   message  10

T
tag
   guidelines for messages  13
   organize for message  9
Rockwell Automation support

Rockwell Automation provides technical information on the web to assist you in using its products. At http://www.rockwellautomation.com/support you can find technical and application notes, sample code, and links to software service packs. You can also visit our Support Center at https://rockwellautomation.custhelp.com for software updates, support chats and forums, technical information, FAQs, and to sign up for product notification updates.

In addition, we offer multiple support programs for installation, configuration, and troubleshooting. For more information, contact your local distributor or Rockwell Automation representative, or visit http://www.rockwellautomation.com/services/online-phone.

Installation assistance

If you experience a problem within the first 24 hours of installation, review the information that is contained in this manual. You can contact Customer Support for initial help in getting your product up and running.

<table>
<thead>
<tr>
<th>United States or Canada</th>
<th>1.440.646.3434</th>
</tr>
</thead>
<tbody>
<tr>
<td>Outside United States or Canada</td>
<td>Use the Worldwide Locator available at <a href="http://www.rockwellautomation.com/locations">http://www.rockwellautomation.com/locations</a>, or contact your local Rockwell Automation representative.</td>
</tr>
</tbody>
</table>

New product satisfaction return

Rockwell Automation tests all of its products to ensure that they are fully operational when shipped from the manufacturing facility. However, if your product is not functioning and needs to be returned, follow these procedures.

<table>
<thead>
<tr>
<th>United States</th>
<th>Contact your distributor. You must provide a Customer Support case number (call the phone number above to obtain one) to your distributor to complete the return process.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Outside United States</td>
<td>Please contact your local Rockwell Automation representative for the return procedure.</td>
</tr>
</tbody>
</table>

Documentation feedback

Your comments will help us serve your documentation needs better. If you have any suggestions on how to improve this document, complete the feedback form, publication RA-DU002.

Rockwell Otomasyon Ticaret A.Ş., Kar Plaza İş Merkezi E Blok Kat:6 34752 İçerenköy, İstanbul, Tel: +90 (216) 5698400

www.rockwellautomation.com